

R&A CONTROLS ENGINEERING VEHICLE CONTROLS & SYSTEM ENGINEERING



Converting Spreadsheet-Based Scenario Definitions to OpenSCENARIO Files

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Presentation Outline

- Introduction
- What Is OpenSCENARIO
- Tool Methodology
- OpenSCENARIO Across Ford
- Demo 1
- Demo 2
- Summary
- Q&A

15 Min.

5 Min.



What Is OpenSCENARIO?



- Open file format to describe dynamic test cases
- Describes complex, synchronized maneuvers (e.g. pre-collision assist, cut-ins, lane centering assist, traffic jam assist)
- The standard describes the ways in which a vehicle moves using stories conditions, acts, and sequences.

Welcome to the World of OpenSCENARIO!

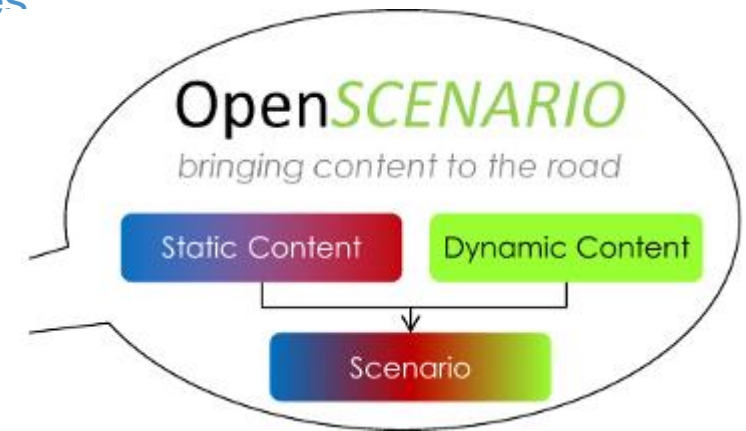
OpenSCENARIO is an **open file format** for the description of dynamic contents in driving simulation applications

This project has been transferred to ASAM e.V. in November 2018. The current website remains active and provides all information until the corresponding infrastructure at ASAM is in place. Thanks to everybody who has contributed to the OpenSCENARIO project so far.

If you want to be informed about the initiative's progress and major events, please register for the newsletter at the ASAM e.V. website

This website is maintained by VIRES Simulationstechnologie GmbH, Germany.

November 2018



OpenSCENARIO
bringing content to the road

Benefits and Pain Points



- Temporary Pain Points
 - Validation of the standard
 - Utilization of the standard
 - Unprecise written definition of the standard
- Long Term Benefits
 - Universally used
 - Shortens scenario generation time e.g. no learning curve or conversion
 - Keeping up with industry
 - Enables the exchange and usability of scenarios agnostic to supplier
 - Large numbers of critical situations can be run across various simulators

```

DoubleLaneChanger.xosc X
C:\Users\kmcgarri\Documents\MATLAB\Consulting\Ford\OpenSCENARIO\Examples\DoubleLaneChanger.xosc
1 <?xml version="1.0" encoding="UTF-8"?>
2 <OpenSCENARIO xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance" xsi:noNamespaceSchemaLocation="
3 <FileHeader revMajor="1" revMinor="0" date="2020-02-21T10:00:00" description="Double Lane Chan
4 <ParameterDeclarations/>
5 <CatalogLocations>
6 <VehicleCatalog> <Storyboard>
7 <Directory path="Catalogs/VehicleCatalogs"/> <Init>
8 </VehicleCatalog> <Actions>
9 <ControllerCatalog> <Private entityRef="Ego">
10 <Directory path="Catalogs/ControllerCatalogs"/> <PrivateAction>
11 </ControllerCatalog> <LongitudinalAction>
12 </CatalogLocations> <SpeedAction>
13 <RoadNetwork> <SpeedActionDynamics dynamicsShape="step" value="0" dynamicsDimension="time"/>
14 <LogicFile filepath="Databases/SampleDatabase.xodr"/> <SpeedActionTarget>
15 </RoadNetwork> <AbsoluteTargetSpeed value="3.61111111111111107e+01"/>
16 <Entities> </SpeedActionTarget>
17 <ScenarioObject name="Ego"> </SpeedAction>
18 <CatalogReference catalogName="VehicleCatalog" ent </LongitudinalAction>
19 <ObjectController> <PrivateAction>
20 <CatalogReference catalogName="ControllerCatalog <TeleportAction>
21 </ObjectController> <Position>
22 </ScenarioObject> <WorldPosition x="1.7024039832784507e+02" y="3.433047995273438e+02" z="0.000000
23 <ScenarioObject name="A1"> </Position>
24 <CatalogReference catalogName="VehicleCatalog" ent </TeleportAction>
25 <ObjectController> </PrivateAction>
26 <CatalogReference catalogName="ControllerCatalog <Private entityRef="A1">
27 </ObjectController> <PrivateAction>
28 </ScenarioObject> <LongitudinalAction>
29 <ScenarioObject name="A2"> <SpeedAction>
30 <CatalogReference catalogName="VehicleCatalog" ent <SpeedActionDynamics dynamicsShape="step" value="0" dynamicsDimension="time"/>
31 <ObjectController> <SpeedActionTarget>
32 <CatalogReference catalogName="ControllerCatalog <AbsoluteTargetSpeed value="4.7222222222222221e+01"/>
33 </ObjectController> </SpeedActionTarget>
34 </ScenarioObject> </SpeedAction>
35 </Entities> </LongitudinalAction>
                <PrivateAction>
                <TeleportAction>
                <Position>
                <WorldPosition x="1.6682571411132812e+02" y="3.3006811523437500e+02" z="0.000000
                </Position>
                </TeleportAction>
                </PrivateAction>
                </PrivateAction>
            
```



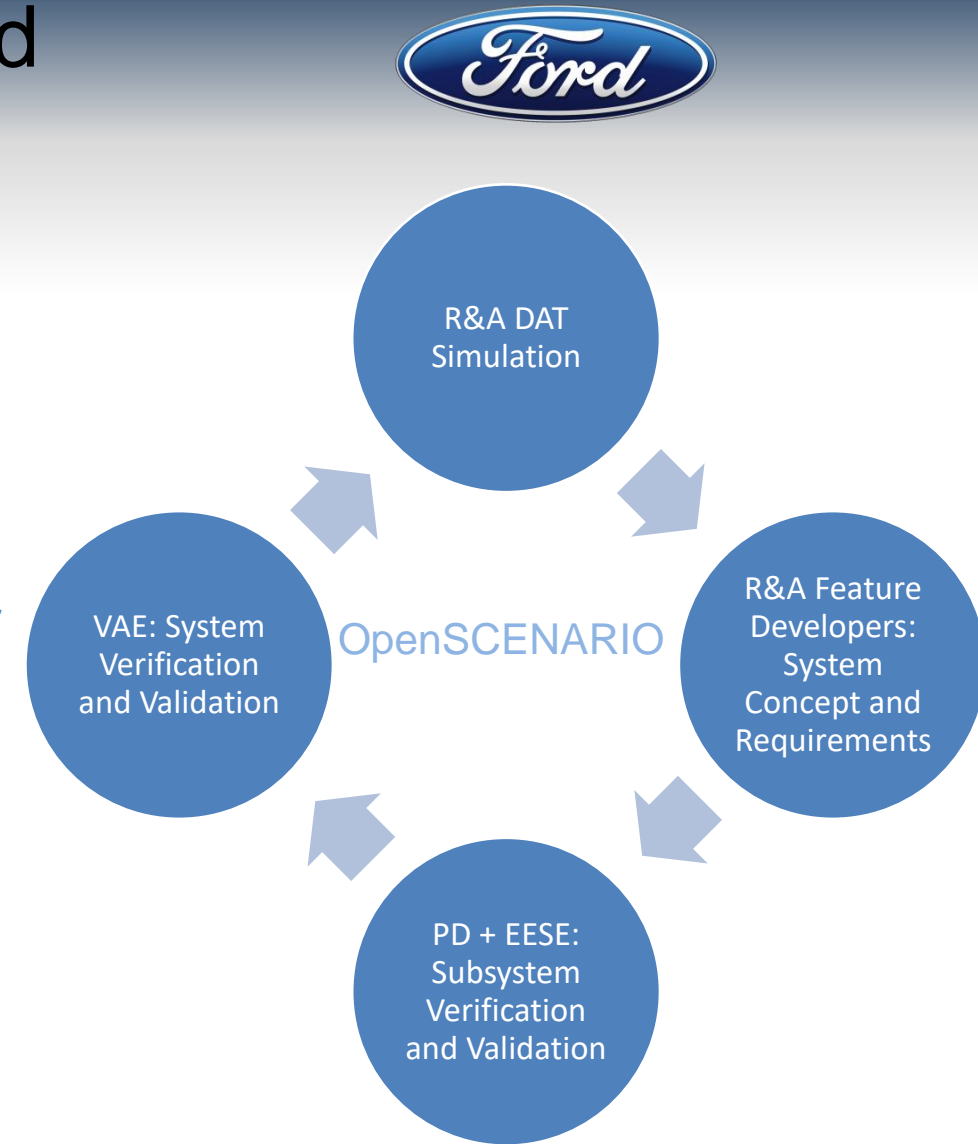
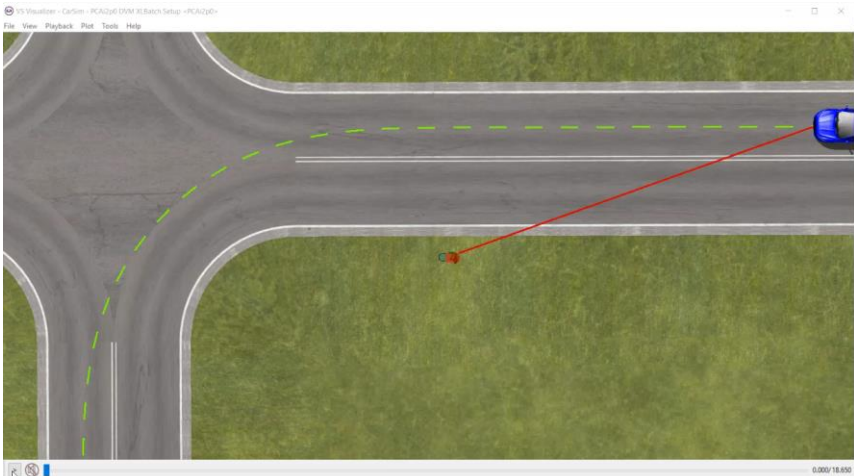
Ford-MathWorks Tool Methodology



- 1.) Investigate OpenSCENARIO constructs and capabilities → Will OpenSCENARIO suffice?
- 2.) Create a methodology to build up automated scenarios using MATLAB/Simulink → What tests will benefit from standardization?
- 3.) Determine method(s) to represent scenario in MATLAB → .mat files, apps, Driving Scenario Designer?
- 4.) Create a tool to enter scenario information → How can we automate the process?
- 5.) Create XML export functionality that matches that of OpenSCENARIO Spec

OpenSCENARIO Across Ford Continued

- Reading and writing back out scenario files for both Open Scenario and Open Drive for CarSim use case
- Agent based traffic scenario testing
- Creating scenes from Lidar and camera data, validating the scene
- App that reads in Test Runs , Road, and Vehicle files from Carmaker and builds up a scenario in driving scenario
- Validation of ADAS feature
- Scenario Creation from L2/L3 road data



FILE VARIABLE CODE SIMULINK ENVIRONMENT RESOURCES

New Script New Live Script New Open Compare Import Data Save Workspace New Variable Open Variable Clear Workspace Favorites Run and Time Clear Commands Simulink Layout Preferences Set Path Parallel Add-Ons Help Community Request Support Learn MATLAB

C:\Users\efoste42\Documents\OpenSCENARIO\App\ExcelImporter

Current Folder

- Name
- OpenSCENARIOoutput
- ~\$SampleTestData.xlsx
- OpenSCENARIOoexporter_From_EXCEL.mlapp
- SampleTestData.xlsx

OpenSCENARIOoexporter_From_EXCEL.mlapp (App)

No details available

Command Window

```
fx >>
```

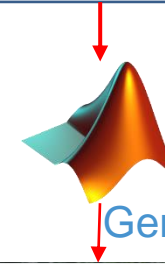
Workspace

Name	Value
------	-------

General Format to OpenSCENARIO App-2



- 2nd app solves the problem of diverse test file formats
 - Benefited general formats (Excel, Word, MagicDraw, ECU-TEST) with ambiguous structure
 - Addressed need for multiple exported catalogs with OpenDRIVE



General Format to OpenSCENARIO App-2

The screenshot shows the 'OpenSCENARIO Exporter' application window. The main area is a form for configuring a host vehicle. The form is divided into several sections: 'Host Information', 'Dynamic Information', 'Camera Information', 'Radar Information', and 'Host Driver'. The 'Host Information' section includes fields for Host Mass (kg), Host Width (m), Host Length (m), Host Height (m), Host Category, Host Name, Catalog Entry Name, and Host Origin. The 'Dynamic Information' section includes fields for Host Wheelbase (m), Host Track Width (m), Host Wheel Diameter (m), Host Max Steering (deg), Host Front Overhang (m), Host Rear Overhang (m), Host Max Deceleration (m/s²), Host Max Speed (kph), and Host Axle Clearance (m). The 'Host Driver' section includes fields for Model, Gender, Eye Distance (cm), Height (m), Age, and Weight (kg). The 'Camera Information' and 'Radar Information' sections include fields for the number of sensors. The 'Export Directory' is set to 'C:\Users\kmcgarr\OneDrive - MathWorks\MATLAB\Consulting\Active\Ford\OpenSCENARIO\Working\ExportOutput'. The 'Export' button is highlighted.

Fill in the required information about the host Vehicle. Use the Camera and Radar Information tabs to provide information about the sensors.

HOME PLOTS APPS

New Script New Live Script New Open Find Files Compare Import Data Save Workspace New Variable Open Variable Clear Workspace Favorites Analyze Code Run and Time Clear Commands Simulink Layout Preferences Set Path Parallel Add-Ons Help Community Request Support Learn MATLAB

FILE VARIABLE CODE SIMULINK ENVIRONMENT RESOURCES

C:\Users\efoste42\Documents\OpenSCENARIO\App\App

Current Folder

- Name
- +importOSC
- +setGet
- +valueChanged
- +write
- Output
- NullSession.mat
- OpenSCENARIOexporter_V7.mlapp
- RouteDefinitions.xlsx
- SampleDatabase_01.xodr
- WorkingTestSession.mat

OpenSCENARIOexporter_V7.mlapp (App)

No details available

Workspace

Name	Value
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Command Window

```
f >>
```

Results/Benefits



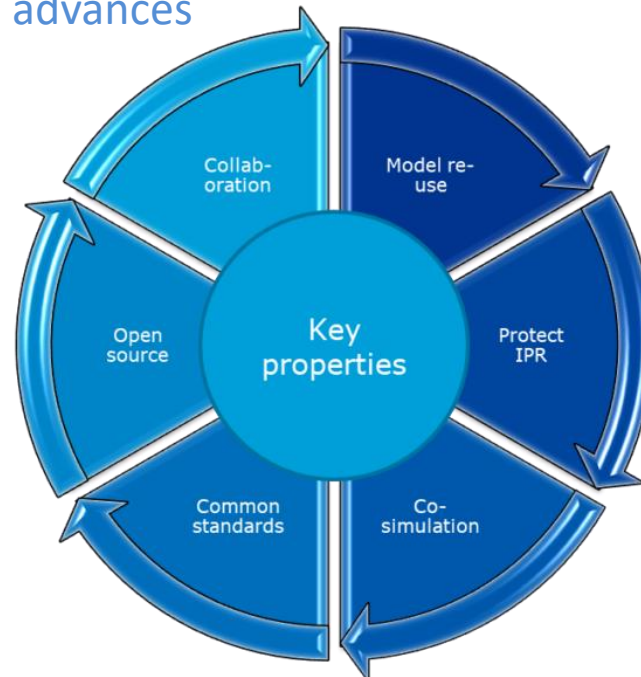
- Through standardization the tool allowed for scenario reuse regardless of the simulation tool and test case format
 - 1st app both showed the resulting scenario in the MathWorks drivingScenario tool as well as exported OpenSCENARIO 0.9.1 files
 - 2nd allowed users to enter information required by OpenSCENARIO by hand to build up scenarios from other documentation
- Unique opportunity to collaborate
- The resulting standard files are stored in GitHub (Ford only)



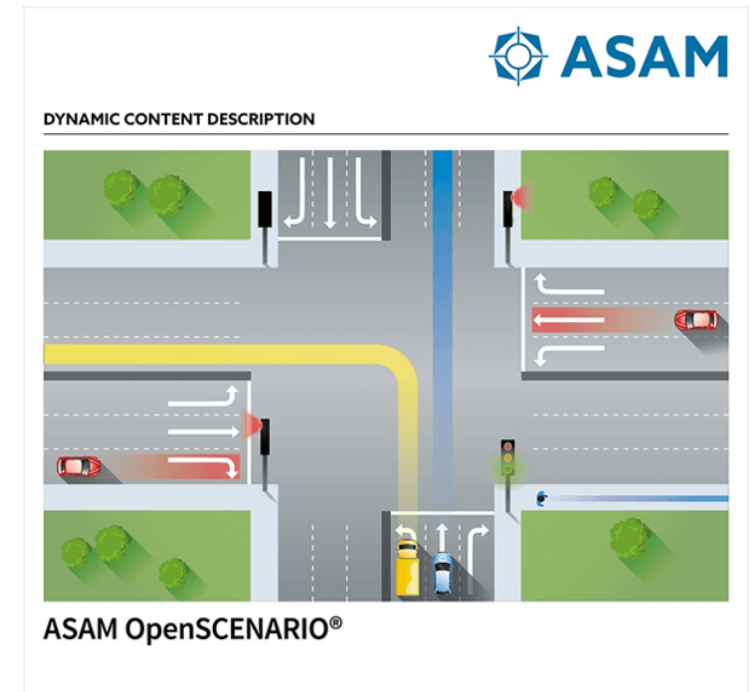
Future Work



- Next steps are to make the files accessible, searchable, findable by groups that didn't create them but want to use them
- MathWorks tools have advanced since the creation of the final version of the app. drivingScenario Designer now exports OpenSCENARIO
- Keep up to date on ASAM OpenSCENARIO advances
- Utilize advancements in current workflow



ASAM OpenSCENARIO V2.0





Thank You!

Q&A